PATENT ABSTRACTS OF JAPAN

(11) Publication number:

05-029134

(43) Date of publication of application: 05.02.1993

(51) Int. CI.

7/16 H01F

F16H 25/20

H01F 7/08

(21) Application number: 03-201142

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(22) Date of filing:

17.07.1991

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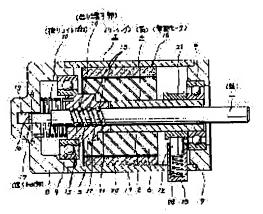
(54) ELECTRIC LINEAR ACTUATOR

(57) Abstract:

PURPOSE: To suppress electric consumption and

hysteresis.

CONSTITUTION: A shaft 1 is supported in a casing 5 permitting displacement only along the shaft direction. A cylinder 4 provided at the periphery of the shaft 1 is supported in the casing 5 permitting only revolution. Elastic force in the revolving direction is applied to the cylinder 4 by a torsion coil spring 10. An electric motor 18 is provided between the casing 5 and the cylinder 4. The electric motor 18 revolves the cylinder 4 in the reverse direction to the elastic force of the torsion coil spring 10 when current is conducted. A feed screw 14 is provided between the cylinder 4 and the axis 1 and a baffle 17 which prevents the revolution of the axis 1 is provided between the casing 5 and the axis 1. Therefore, the axis 1 displaces in the axis direction when the cylinder 4 is revolved.



LEGAL STATUS

[Date of request for examination] [Date of sending the examiner's decision of rejection]

[Kind of final disposal of application other than the examiner's decision of rejection or application converted registration]

[Date of final disposal for application]

[Patent number]

[Date of registration]

[Number of appeal against examiner's decision of rejection]

[Date of requesting appeal against examiner's decision of rejection]

[Date of extinction of right]

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DETAILED DESCRIPTION

[Detailed Description of the Invention]

[0001]

[Industrial Application] Since the flow control valve prepared for example, in the middle of various hydraulic circuits is driven, the electromotive linear actuator concerning this invention is used. [0002]

[Description of the Prior Art] For example, in order to drive the flow control valve prepared in the hydraulic circuit prepared in an automobile based on the instructions from a controller, the linear actuator of an electric formula is needed. For this reason, the electromotive linear actuator which combined a solenoid and compression spring is used from the former.

[0003] the electromotive linear actuator known from this former -- the variation rate of a rod etc. -- a member -- the aforementioned compression spring -- one side -- energizing -- this variation rate -- energizing to the aforementioned solenoid, when the variation rate of the member needs to be carried out -- the above -- a variation rate -- the variation rate of the member is resisted and carried out to the elasticity of the aforementioned compression spring a variation rate -- the variation rate of a member -- an amount -- the amount of energization to the aforementioned solenoid -- controlling -- this solenoid -- the above -- a variation rate -- it adjusts by changing the size of the force of attracting a member That is, to the position where the elasticity of the aforementioned compression spring and the suction force of the aforementioned solenoid balance, the aforementioned displacement member is displaced and stops.

[0004]

[Problem(s) to be Solved by the Invention] However, since it is necessary to pass big current to a solenoid in case the variation rate of the displacement member is carried out in the case of the conventional electromotive linear actuator using the above solenoids, for example, when it is used for a switch of the hydraulic circuit of an automobile, it becomes the cause which applies a burden to a dc-battery, and is not desirable.

[0005] moreover, the thing for which the elasticity of compression spring and the suction force of a solenoid are balanced -- the above -- a variation rate -- the variation rate of a member -- although an amount is adjusted -- compression spring -- a variation rate -- since the structure which energizes a member has a large hysteresis, ***** it passes the same current as the aforementioned solenoid -- the above -- a variation rate -- the case where another side is made to carry out the variation rate of the member to the case where a variation rate is carried out to one side -- a variation rate -- For this reason, it was difficult to fine-adjust the opening of a flow control valve etc.

[0006] The electromotive linear actuator of this invention cancels above un-arranging. [0007]

[Means for Solving the Problem] The electromotive linear actuator of this invention the relative rotation to this shaft among the cylinder prepared as free, and this cylinder and the aforementioned

shaft to a shaft, this shaft, and this heart The elastic member to which it is prepared between a member and the portion of fixation, and while only rotation is free gives the elasticity of a hand of cut to the member of one of these, The delivery thread part to which it is prepared between the periphery side of the aforementioned shaft, and the inner skin of the aforementioned cylinder, and the variation rate of the member of another side of the aforementioned shaft and the cylinders is carried out [shaft orientations] with rotation of aforementioned one member, Casing prepared in the circumference of the aforementioned cylinder, and the electrical motor which it is prepared inside this casing, and the elasticity of the aforementioned elastic member is resisted [electrical motor] and makes it rotate aforementioned one member with energization, It is prepared between the aforementioned casing and the member of aforementioned another side, and although the variation rate covering the shaft orientations of the member of this another side is permitted, it consists of the baffle sections which prevent rotation.

[0008]

[Function] In the case of the electromotive linear actuator of this invention constituted as mentioned above, on the other hand at the time of un-energizing to an electrical motor, one member of a shaft and the cylinders rotates to ** by the elasticity of an elastic member. Under the present circumstances, in order for the member of another side of the aforementioned shaft and the cylinders to have rotation prevented by the baffle section, the member of this another side is made to carry out the variation rate of it even to a shaft-orientations end by the delivery thread part.

[0009] Moreover, if it energizes to an electrical motor, aforementioned one member will rotate according to the amount of energization. That is, the member of one of these stops in the state where it rotated even in the state where the rotation torque of the aforementioned electrical motor which becomes settled according to the amount of energization, and the elasticity of the aforementioned elastic member balance. And the member of aforementioned another side displaces towards the shaft-orientations other end with rotation of aforementioned one member by the aforementioned delivery thread part.

[0010]

[Example] <u>Drawing 1</u> -2 show the example of this invention. The shaft 1 prepared in the core is displaced only to shaft orientations (longitudinal direction of <u>drawing 1</u>), without rotating, and the valve element of a flow control valve etc. is driven (a parallel displacement is carried out). The cylinder 4 which combined the first cylinder part 2 and the second cylinder part 3 of each other with the circumference of this shaft 1 in series is formed in this shaft 1 and this heart, and casing 5 is further formed in the circumference of this cylinder 4.

[0011] Connecting through the armature 6 mentioned later, in the first cylinder part 2, the second cylinder part 3 is supporting only rotation free through anti-friction bearings 9 and 9 on the inner circumference edge of the front lid 7 of the aforementioned casing 5 at the opening marginal part of the back lid 8, respectively among the first cylinder part 2 of the above and the second cylinder part 3 which constitute the aforementioned cylinder 4.

[0012] Moreover, the end of the twisted coil spring 10 which is an elastic member is stopped to the end face of the second cylinder part 3 of the above, and the other end of this twisted coil spring 10 is stopped to the inside of the lid 8 after the above, respectively. Consequently, it will be in the state where the elasticity of a hand of cut was given to the cylinder 4 containing the second cylinder part 3 of the above.

[0013] Moreover, a ball screw mechanism is constituted and the delivery thread part 14 to which the variation rate of the aforementioned shaft 1 is carried out [shaft orientations] consists of forming two or more balls 13 and 13 between the spiral slot 11 formed in the periphery side of the aforementioned shaft 1, and the spiral slot 12 formed in the inner skin of the second cylinder part 3 which constitutes the aforementioned cylinder 4 with rotation of the second cylinder part 3 of the above. On the other hand, the non-pillar section 16 which formed the crevice 15 of a non-round shape as shown in

drawing 2, and was formed in this crevice 15 at the edge of the aforementioned shaft 1 is inserted in the inside center section of the lid 8 after the above. And by engagement to this non-pillar section 16 and the aforementioned crevice 15, although the variation rate covering the shaft orientations of the aforementioned shaft 1 is permitted, the baffle section 17 which prevents rotation of this shaft 1 is constituted.

[0014] Furthermore, inside the aforementioned casing 5, the electrical motor 18 which the elasticity of the aforementioned twisted coil spring 10 is resisted [electrical motor], and makes it rotate the aforementioned cylinder 4 with energization is formed. That is, a permanent magnet 20 is fixed to the inner skin of the body 19 which constitutes the drum section of the aforementioned casing 5, and the periphery side of an armature 6 which built inner skin, and the first cylinder part 2 of the above and the second cylinder part 3 of this permanent magnet 20, and was established is made to counter. The commutator 21 is fixed to the periphery side of the first cylinder part 2 of the above, and the inner end face of a brush 22 is made to **** to the periphery side of this commutator 21. This brush 22 is fitted in in the electrode holder 23 fixed to the aforementioned body 19 considering the variation rate covering the diameter direction of this body 19 as free, and is pressed towards the aforementioned commutator 21 by compression spring 24.

[0015] In the case of the electromotive linear actuator of this invention constituted as mentioned above, on the other hand at the time of un-energizing to an electrical motor 18, a cylinder 4 rotates to ** by the elasticity of a twisted coil spring 10. Under the present circumstances, the aforementioned shaft 1 does not rotate with the aforementioned cylinder 4 by engagement to the inner skin of a crevice 15 and the periphery side of the non-pillar section 16 which constitute the baffle section 17. The aforementioned shaft 1 is made to carry out a variation rate even to a shaft-orientations end for this reason by the aforementioned delivery thread part 14.

[0016] Moreover, if it energizes to an electrical motor 18 through the aforementioned brush 22, the aforementioned cylinder 4 will rotate according to the amount of energization. That is, this cylinder 4 stops in the state as it is, unless it rotates even in the state where the rotation torque of the aforementioned electrical motor 18 which becomes settled according to the amount of energization, and the elasticity of the aforementioned twisted coil spring 10 balance and the amount of energization is changed.

[0017] Since the delivery thread part 14 which is a ball screw mechanism is formed between the inner skin of the second cylinder part 3 and the periphery sides of the aforementioned shaft 1 which constitute the aforementioned cylinder 4, the aforementioned shaft 1 displaces towards the shaft-orientations other end with rotation of the aforementioned cylinder 4 by the aforementioned delivery thread part 14. Therefore, if the valve element of a flow control valve etc. is supported at the edge of the aforementioned shaft 1, control of flow by this flow control valve can be performed by changing the amount of energization to the aforementioned electrical motor 18.

[0018] A twisted coil spring 10 has the small hysteresis of the spring itself compared with the hauling spring built into the linear actuator of the aforementioned conventional solenoid formula, and since the structure for moreover changing the turning effort of an electrical motor 18 into the variation rate of a shaft 1 is also constituted by the ball screw mechanism in which friction loss is small, the hysteresis as the whole linear actuator becomes a small thing. Moreover, since the delivery thread part 14 by the aforementioned ball screw mechanism increases the torque of an electrical motor 18 and it transmits to the aforementioned shaft 1, in order to carry out the variation rate of this shaft 1 [shaft orientations], the value of the current energized to the aforementioned electrical motor 18 is comparatively small, and ends.

[0019] In addition, when it constitutes the electromotive linear actuator of this invention, contrary to the case of illustration, a shaft 1 can be rotated and it can also consider as the structure of carrying out the variation rate of the cylinder 4 to shaft orientations.

[0020]

[Effect of the Invention] In order that the electromotive linear actuator of this invention may be constituted as it was stated above, and it may act, it can acquire the big force by few power consumption, and, moreover, becomes possible [controlling various devices, such as a flow control valve, delicately] as a small electromotive linear actuator of a hysteresis.

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PRIOR ART

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EFFECT OF THE INVENTION

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[Translation done.]

CLIPPEDIMAGE= JP405029134A

PAT-NO: JP405029134A

DOCUMENT-IDENTIFIER: JP 05029134 A

TITLE: ELECTRIC LINEAR ACTUATOR

PUBN-DATE: February 5, 1993

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APPL-NO: JP03201142

APPL-DATE: July 17, 1991

INT-CL (IPC): H01F007/16;F16H025/20;H01F007/08

US-CL-CURRENT: 310/12

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1 is supported in the casing 5 permitting only revolution. Elastic force in

the revolving direction is applied to the cylinder 4 by a torsion coil spring

10. An electric motor 18 is provided between the casing 5 and the cylinder 4.

The electric motor 18 revolves the cylinder 4 in the reverse direction to the

elastic force of the torsion coil spring 10 when current is conducted. A feed

screw 14 is provided between the cylinder 4 and the axis 1 and a baffle 17

which prevents the revolution of the axis 1 is provided between the casing 5 and the axis 1. Therefore, the axis 1 displaces in the axis direction when the cylinder 4 is revolved.

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(19)日本国特許庁(JP)

(12) 公開特許公報(A)

(11)特許出願公開番号

特開平5-29134

(43)公開日 平成5年(1993)2月5日

F 1 6 H	25/20 7/08	Е Н В	8207—3 J 8207—3 J 7135—5E		審査請求	未請求	請求項の数1(全 4 頁)
(21)出願番号		特顧平3-201142		(71)出顧人 000004204 日本精工株式会社			

群馬

平成3年(1991)7月17日

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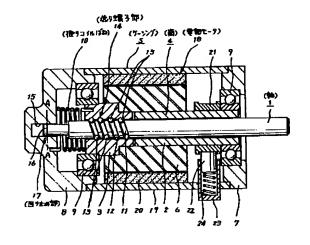
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(54)【発明の名称】 電動式リニアアクチユエータ

(57)【要約】

(22)出願日

【目的】電力消費並びにヒステリシスを小さく抑える。 【構成】軸1をケーシング5の内側に、軸方向に亙る変位のみ自在に支持する。軸1の周囲に設けた筒4を前記ケーシング5の内側に、回転のみ自在に支持する。捩りコイルばね10により前記筒4に、回転方向の弾力を付与する。ケーシング5と筒4との間に電動モータ18を設ける。この電動モータ18は、通電に伴なって前記筒4を、捩りコイルばね10の弾力方向と逆方向に回転させる。筒4と軸1との間には送り螺子部14を、ケーシング5と軸1との間には送り螺子部14を、ケーシング5と軸1との間にはこの軸1の回転を阻止する周り止め部17を、それぞれ設ける。従って、前記筒4の回転に伴なって前記軸1が、軸方向に変位する。



【特許請求の範囲】

. . .

【請求項1】 軸と、この軸と同心に、この軸に対する 相対的回転を自在として設けられた筒と、この筒と前記 軸との内で、回転のみ自在な一方の部材と固定の部分と の間に設けられ、この一方の部材に回転方向の弾力を付 与する弾性部材と、前記軸の外周面と前記筒の内周面と の間に設けられ、前記一方の部材の回転に伴なって、前 記軸と筒との内の他方の部材を、軸方向に亙って変位さ せる送り螺子部と、前記筒の周囲に設けられたケーシン グと、このケーシングの内側に設けられて、通電に伴な って前記一方の部材を、前記弾性部材の弾力に抗して回 転させる電動モータと、前記ケーシングと前記他方の部 材との間に設けられ、この他方の部材の軸方向に亙る変 位は許容するが回転を阻止する回り止め部とから成る電 動式リニアアクチュエータ。

【発明の詳細な説明】

[0001]

【産業上の利用分野】この発明に係る電動式リニアアク チュエータは、例えば各種油圧回路の途中に設ける流量 制御弁等を駆動する為に利用する。

【従来の技術】例えば自動車に設けられる油圧回路に設

[0002]

ける流量制御弁等を、制御器からの指令に基づいて駆動 する為には、電動式のリニアアクチュエータが必要とな る。この為従来から、ソレノイドと圧縮ばねとを組み合 わせた電動式リニアアクチュエータが使用されている。 【0003】この従来から知られた電動式リニアアクチ ュエータは、ロッド等の変位部材を前記圧縮ばねによっ て一方に付勢しておき、この変位部材を変位させる必要 前記変位部材を、前記圧縮ばねの弾力に抗して変位させ るものである。変位部材の変位量は、前記ソレノイドへ の通電量を制御し、このソレノイドが前記変位部材を吸 引する力の大きさを変える事で調節する。即ち、前記変 位部材は、前記圧縮ばねの弾力と前記ソレノイドの吸引 力とが釣り合う位置迄変位して停止する。

[0004]

【発明が解決しようとする課題】ところが、上述の様な ソレノイドを利用した従来の電動式リニアアクチュエー タの場合、変位部材を変位させる際に、ソレノイドに大 40 きな電流を流す必要がある為、例えば自動車の油圧回路 の切り換えに使用した場合、バッテリーに負担をかける 原因となり、好ましくない。

【0005】又、圧縮ばねの弾力とソレノイドの吸引力 とを釣り合わせる事で、前記変位部材の変位量を調節す るが、圧縮ばねにより変位部材を付勢する構造はヒステ リシスが大きい為、前記ソレノイドに同じ電流を流した としても、前記変位部材を一方に変位させる場合と他方 に変位させる場合とで変位量が大きく異なってしまう。 この為、流量制御弁の開度を微調節する事等が難しかっ 50 10の他端を前記後蓋8の内面に、それぞれ係止してい

た。

【0006】本発明の電動式リニアアクチュエータは、 上述の様な不都合を解消するものである。

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[0007]

【課題を解決するための手段】本発明の電動式リニアア クチュエータは、軸と、この軸と同心に、この軸に対す る相対的回転を自在として設けられた筒と、この筒と前 記軸との内で、回転のみ自在な一方の部材と固定の部分 との間に設けられ、この一方の部材に回転方向の弾力を 付与する弾性部材と、前記軸の外周面と前記筒の内周面 との間に設けられ、前記一方の部材の回転に伴なって、 前記軸と筒との内の他方の部材を、軸方向に亙って変位 させる送り螺子部と、前記筒の周囲に設けられたケーシ ングと、このケーシングの内側に設けられて、通電に伴 なって前記一方の部材を、前記弾性部材の弾力に抗して 回転させる電動モータと、前記ケーシングと前記他方の 部材との間に設けられ、この他方の部材の軸方向に亙る 変位は許容するが回転を阻止する回り止め部とから構成 される。

[0008] 20

【作用】上述の様に構成される本発明の電動式リニアア クチュエータの場合、電動モータへの非通電時には、軸 と筒との内の一方の部材が、弾性部材の弾力により一方 向に回転する。この際、前記軸と筒との内の他方の部材 は、回り止め部により回転を阻止される為、送り螺子部 によりこの他方の部材が、軸方向一端に迄変位させられ る。

【0009】又、電動モータに通電すると、前記一方の 部材が、通電量に応じて回転する。即ち、この一方の部 が生じた場合には、前記ソレノイドに通電する事により 30 材は、通電量に応じて定まる前記電動モータの回転トル クと、前記弾性部材の弾力とが釣り合う状態に迄回転し た状態で停止する。そして、前記一方の部材の回転に伴 ない、前記送り螺子部により前記他方の部材が、軸方向 他端に向けて変位する。

[0010]

【実施例】図1~2は本発明の実施例を示している。中 心部に設けられた軸1は、回転する事なく軸方向(図1 の左右方向) にのみ変位し、流量制御弁の弁体等を駆動 する (平行移動させる)。この軸1の周囲には、第一筒 部2と第二筒部3とを互いに直列に組み合わせた筒4 が、この軸1と同心に設けられており、更に、この筒4 の周囲には、ケーシング5が設けられている。

【0011】後述する電機子6を介して接続され、前記 筒4を構成する、前記第一筒部2と第二筒部3との内、 第一筒部2は前記ケーシング5の前蓋7の内周縁に、第 二筒部3は後蓋8の開口縁部に、それぞれ転がり軸受 9、9を介して、回転のみ自在に支承している。

【0012】又、弾性部材である捩りコイルばね10の 一端を、前記第二筒部3の端面に、この捩りコイルばね る。この結果、前記第二筒部3を含む筒4には、回転方 向の弾力が付与された状態となる。

【0013】又、前記軸1の外周面に形成した螺旋溝1 1と、前記筒4を構成する第二筒部3の内周面に形成し た螺旋溝12との間には、複数のボール13、13を設 ける事で、ボール螺子機構を構成し、前記第二筒部3の 回転に伴なって、前記軸1を軸方向に亙って変位させる 送り螺子部14を構成している。一方、前記後蓋8の内 面中央部には、図2に示す様な非円形の凹部15を形成 しており、この凹部15に、前記軸1の端部に形成した 10 向に亙って変位させる為に、前記電動モータ18に通電 非円柱部16を挿入している。そして、この非円柱部1 6と前記凹部15との係合により、前記軸1の軸方向に 亙る変位は許容するが、この軸1の回転を阻止する回り 止め部17を構成している。

【0014】更に、前記ケーシング5の内側には、通電 に伴なって前記筒4を、前記捩りコイルばね10の弾力 に抗して回転させる電動モータ18を設けている。即 ち、前記ケーシング5の胴部を構成する円筒部19の内 周面に永久磁石20を固定し、この永久磁石20の内周 面と、前記第一筒部2と第二筒部3とに掛け渡して設け 20 られた電機子6の外周面とを対向させている。前記第一 筒部2の外周面には整流子21を固定しており、この整 流子21の外周面に、ブラシ22の内端面を摺接させて いる。このブラシ22は、前記円筒部19に固設された ホルダ23内に、この円筒部19の直径方向に亙る変位 を自在として嵌装され、圧縮ばね24により、前記整流 子21に向け押圧されている。

【0015】上述の様に構成される本発明の電動式リニ アアクチュエータの場合、電動モータ18への非通電時 には、捩りコイルばね10の弾力により筒4が、一方向 30 6 電機子 に回転する。この際前記軸1は、回り止め部17を構成 する凹部15の内周面と非円柱部16の外周面との係合 により、前記筒4と共に回転する事はない。この為、前 記送り螺子部14により前記軸1が、軸方向一端に迄変 位させられる。

【0016】又、前記ブラシ22を介して電動モータ1 8に通電すると、前記筒4が、通電量に応じて回転す る。即ち、この筒4は、通電量に応じて定まる前記電動 モータ18の回転トルクと、前記捩りコイルばね10の 弾力とが釣り合う状態に迄回転し、通電量を変えない限 40 16 非円柱部 り、そのままの状態で停止する。

【0017】前記筒4を構成する第二筒部3の内周面と 前記軸1の外周面との間には、ボール螺子機構である送 り螺子部14が設けられている為、前記筒4の回転に伴 ない、前記送り螺子部14により前記軸1が、軸方向他 端に向けて変位する。従って、前記軸1の端部に流量制 御弁の弁体等を支持すれば、前記電動モータ18への通 電量を変える事で、この流量制御弁による流量制御を行 なえる。

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【0018】 捩りコイルばね10は、前記従来のソレノ イド式のリニアアクチュエータに組み込まれている引っ 張りばねに比べて、ばね自体のヒステリシスが小さく、 しかも電動モータ18の回転力を軸1の変位に変換する 為の構造も、摩擦損失の小さなボール螺子機構により構 成されている為、リニアアクチュエータ全体としてのヒ ステリシスは小さなものとなる。又、前記ボール螺子機 構による送り螺子部14が、電動モータ18のトルクを 増大させてから前記軸1に伝達する為、この軸1を軸方 する電流の値が、比較的小さくて済む。

【0019】尚、本発明の電動式リニアアクチュエータ を構成する場合に、図示の場合とは逆に、軸1を回転さ せ、筒4を軸方向に変位させる構造とする事も出来る。 [0020]

【発明の効果】本発明の電動式リニアアクチュエータ は、以上に述べた通り構成され作用する為、少ない電力 消費で大きな力を得る事が出来、しかもヒステリシスの 小さな電動式リニアアクチュエータとして、流量制御弁 等、各種機器を微妙に制御する事が可能となる。

【図面の簡単な説明】

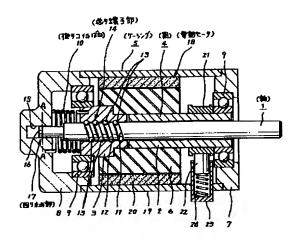
【図1】本発明の実施例を示す断面図。

【図2】図1の拡大A-A断面図。

【符号の説明】

- 1 軸
- 2 第一筒部
- 3 第二筒部
- 4 筒
- 5 ケーシング
- - 7 前蓋
 - 8 後蓋
 - 9 転がり軸受
 - 10 捩りコイルばね
 - 11 螺旋溝
 - 12 螺旋溝
 - 13 ボール
 - 14 送り螺子部
 - 15 凹部
 - - 17 回り止め部
 - 18 電動モータ
 - 19 円筒部
 - 20 永久磁石
 - 21 整流子
 - 22 ブラシ
 - 23 ホルダ
 - 24 圧縮ばね

【図1】



【図2】

